%Алгоритм управления БО

function vihod=algoritm4model(Fpb1,Fpb2,Fpb3,Fpb4,Fpb5,w,a,n)

wt=w;

at=a;

nt=n;

t=80;

Fid=[24 32.1 23.3 11 9.5];

x=[1.5 4.5 8 12.5 17.5];

koefficientbegin

korrektsiya\_po\_vlazhnosti

korrektsiya\_po\_uglu

korrektsiya\_po\_skorosti

Fbo=gransostav\_na\_vihode (Fpb,t,kwan)

R=raznost(Fbo,Fid,x)

optimizatsiya3

Fbo=gransostav\_na\_vihode (Fpb,t,k)

R=raznost(Fbo,Fid,x)

vihod=[Fbo(1) Fbo(2) Fbo(3) Fbo(4) Fbo(5) k(1) k(2) k(5) k(9) wt a n R]